

- **Raspberry Pi Zero 2 W** consumed
 - only **0.68 W** in *idle mode*
 - about **2.05 W** at *5-second polling intervals*
 - consistently **~50% less** than Raspberry Pi 5
 - **E-ink display** had **minimal energy impact**
 - **Dynamic polling** logic significantly **reduced data reads** during inactivity
 - System supports **reliable operation** in **off-grid** field environments
 - Enables **longer runtime, lower energy waste, and smarter monitoring**
- These results confirm that our system is **well-suited** for energy-constrained **agricultural robotics**, combining low power use with real-time capability.

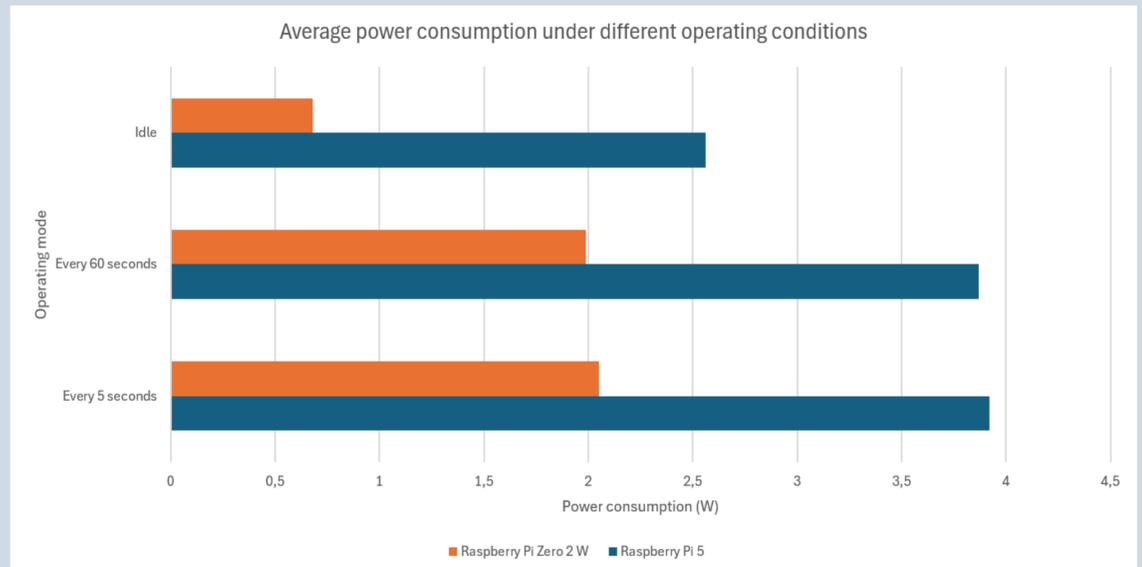


Fig 1. Average power consumption under different operating conditions.

Introduction

Battery-powered agricultural robots require efficient energy management to operate reliably in remote and off-grid environments. Continuous monitoring of battery parameters—voltage, current, temperature, and State of Charge (SoC)—is essential to prevent failures and extend runtime. This project presents a compact, energy-efficient battery monitoring system integrated with a CAN-based Battery Management System (BMS). It collects full-pack and cell-level data, logs it into an SQLite database, and offers both local and remote access through a web-based interface. The system's modular, low-power design enables long-term deployment in demanding field conditions.

Methodology

The system uses a Raspberry Pi Zero 2 W paired with a CAN interface to collect data from a lithium-ion Battery Management System (BMS). Key parameters—voltage, current, temperature, and SoC—are read via CAN bus and stored in an SQLite database. A Python-based monitoring script dynamically adjusts polling intervals based on battery conditions to reduce power usage. An e-ink display shows real-time data locally, while a web-based API enables remote access for diagnostics and performance tracking.



Fig 2. Measuring power draw

Results

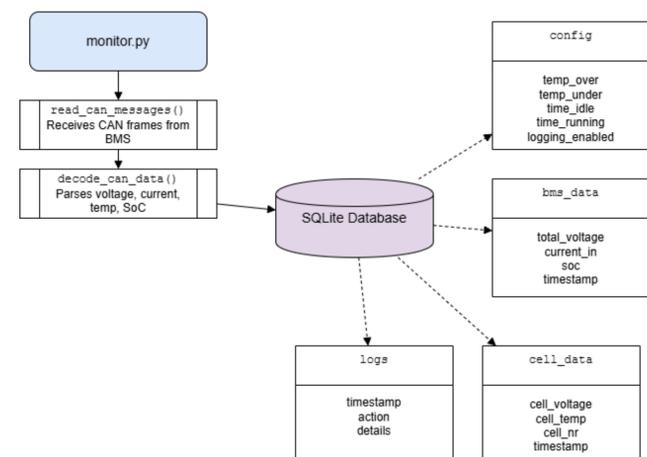


Fig 3. Battery data collection and storage architecture with SQLite and monitoring functions.

- The system **successfully logged** real-time battery data via **CAN bus**.
- Data included **voltage, current, temperature, SoC, and cell-level details**.
- All data was stored in a structured **SQLite database**, enabling efficient queries.
- System operated reliably in **field-like conditions** with **low energy use**.
- **Monitoring frequency** adapted to changing battery conditions.
- Local interface (e-ink) and remote API ensured **dual access** to data.
- The system architecture is ready for **AI-based analysis**, including:
 - **Battery degradation prediction**
 - **Charging pattern optimization**
 - **Remaining Useful Life (RUL) estimation**

Total Voltage	56,5 V
Current IN	0 A
Current OUT	38 A
Current Battery	38 A
Energy stored	4,7 kWh
Battery capacity	5,3 kWh
SOC	89 %

Cell: 1 T: 18,2 C U: 3,54 V	Cell: 2 T: 18,3 C U: 3,48 V	Cell: 3 T: 18,3 C U: 3,54 V	Cell: 4 T: 18,2 C U: 3,49 V
Cell: 5 T: 18,3 C U: 3,6 V	Cell: 6 T: 19,4 C U: 3,52 V	Cell: 7 T: 19,6 C U: 3,54 V	Cell: 8 T: 18,3 C U: 3,54 V
Cell: 9 T: 18,3 C U: 3,54 V	Cell: 10 T: 19,1 C U: 3,54 V	Cell: 11 T: 19,5 C U: 3,47 V	Cell: 12 T: 18,3 C U: 3,54 V
Cell: 13 T: 18,3 C U: 3,55 V	Cell: 14 T: 18,5 C U: 3,54 V	Cell: 15 T: 18,5 C U: 3,53 V	Cell: 16 T: 18,4 C U: 3,54 V

Fig 4. User interface on e-ink screen

These results demonstrate that the system not only performs **robust real-time monitoring** but also **lays the groundwork** for advanced analytics and **predictive maintenance** using machine learning.